## B+ Tree and Hashing



- B+ Tree Properties
- B+ Tree Searching
- B+ Tree Insertion
- B+ Tree Deletion
- Static Hashing
- Extendable Hashing
- Questions in pass papers


## - Balanced Tree

- Same height for paths from root to leaf
- Given a search-key K, nearly same access time for different K values
$-\mathrm{B}+$ Tree is constructed by parameter $\mathbf{n}$
- Each Node (except root) has $\lceil\mathrm{n} / 2\rceil$ to n pointers
- Each Node (except root) has $\lceil n / 2\rceil-1$ to $n-1$ search-key values


General case for n


- Search keys are sorted in order
$-\mathrm{K}_{1}<\mathrm{K}_{2}<\ldots<\mathrm{K}_{\mathrm{n}-1}$
-Non-leaf Node
-Each key-search values in subtree $\mathrm{S}_{\mathrm{i}}$ pointed by $\mathrm{P}_{\mathrm{i}}<\mathrm{K}_{\mathrm{i}},>=\mathrm{K}_{\mathrm{i}-1}$

Key values in $\mathrm{S}_{1}<\mathrm{K}_{1}$
$\mathrm{K}_{1}<=$ Key values in $\mathrm{S}_{2}<\mathrm{K}_{2}$
-Leaf Node
$-P_{i}$ points record or bucket with
search key value $K_{i}$
${ }^{-} \mathrm{P}_{\mathrm{n}}$ points to the neighbor leaf
$-\mathrm{P}_{\mathrm{i}}$ points record or bucket wit
search key value $\mathrm{K}_{\mathrm{i}}$
${ }^{-\mathrm{P}_{\mathrm{n}}}$ points to the neighbor leaf Record of $\mathrm{K}_{1}$
$-\mathrm{P}_{\mathrm{i}}$ points record or bucket with
search key value $\mathrm{K}_{\mathrm{i}}$
$-\mathrm{P}_{\mathrm{n}}$ points to the neighbor leaf node


- Given a search-value k
- Start from the root, look for the largest searchkey value $\left(\mathrm{K}_{\mathrm{l}}\right)$ in the node $<=\mathrm{k}$
- Follow pointer $\mathrm{P}_{1+1}$ to next level, until reach a leaf node $\quad \mathrm{K}_{1}<=\mathrm{k}<\mathrm{K}_{1+1}$

- If k is found to be equal to $\mathrm{K}_{1}$ in the leaf, follow $\mathrm{P}_{1}$ to search the record or bucket

- Overflow
- When number of search-key values exceed n-1

| 7 | 9 | 13 | 15 | Insert 8 |
| :--- | :--- | :--- | :---: | :--- |

## -Leaf Node

-Split into two nodes:
$-1^{\text {st }}$ node contains $\lceil(\mathrm{n}-1) / 2\rceil$ values
$-2^{\text {nd }}$ node contains remaining values
-Copy the smallest search-key value of the $2^{\text {nd }}$ node to parent node


- Overflow
- When number of search-key values exceed n-1

| 7 | 9 | 13 | 15 | Insert 8 |
| :--- | :--- | :--- | :--- | :--- |

## -Non-Leaf Node

- Split into two nodes:
$-1^{\text {st }}$ node contains $\lceil\mathrm{n} / 2\rceil-1$ values
-Move the smallest of the remaining values, together with pointer, to the parent
$-2^{\text {nd }}$ node contains the remaining values

- Example 1: Construct a $\mathrm{B}^{+}$tree for (1, $4,7,10,17,21,31,25,19,20,28,42)$ with $\mathrm{n}=4$.

- $1,4,7,10,17,21,31,25,19,20,28,42$


- $1,4,7,10,17,21,31,25,19,20,28,42$

- Example 2: n=3, insert 4 into the following B+Tree


- Underflow

| $9 \mid$ | Delete 10 |
| :---: | :--- | :--- |

- When number of search-key values $<\lceil\mathrm{n} / 2\rceil-1$
-Leaf Node
-Redistribute to sibling
-Right node not less than left node
-Replace the between-value in parent by their smallest value of the right node
- Merge (contain too few entries)

- Move all values, pointers to left node
-Remove the between-value in parent




## -Non-Leaf Node

-Redistribute to sibling
-Through parent

-Right node not less than left node

-Merge (contain too few entries)
-Bring down parent
 node
-Delete the right node, and pointers in parent


- Example 3: n=3, delete 3


- Example 4: Delete 28, 31, 21, 25, 19

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- A hash function $h$ maps a search-key value K to an address of a bucket
- Commonly used hash function hash value $\bmod n_{B}$ where $n_{B}$ is the no. of buckets
- E.g. $\mathrm{h}($ Brighton $)=(2+18+9+7+8+20+15+14) \mathrm{mod}$ $10=93 \bmod 10=3$

No. of buckets $=10$



- Hash function returns $\mathbf{b}$ bits
- Only the prefix i bits are used to hash the item
- There are $2^{\mathbf{i}}$ entries in the bucket address table
- Let $\mathbf{i}_{\mathbf{j}}$ be the length of the common hash prefix for data bucket $\mathbf{j}$, there is $\mathbf{2}^{\left({ }^{(-i} \mathbf{j}\right)}$ entries in bucket address table points to $\mathbf{j}$
- Splitting (Case $1 \mathrm{i}_{\mathrm{j}}=\mathrm{i}$ )
- Only one entry in bucket address table points to data bucket j
- $i++$; split data bucket $j$ to $j, z ; i_{j}=i_{z}=i$, rehash all items previously in j ;

- Splitting (Case $2 \mathrm{i}_{\mathrm{j}}<\mathrm{i}$ )
- More than one entry in bucket address table point to data bucket j
- split data bucket j to $\mathrm{j}, \mathrm{z} ; \mathrm{i}_{\mathrm{j}}=\mathrm{i}_{\mathrm{z}}=\mathrm{i}_{\mathrm{j}}+1$; Adjust the pointers previously point to j to j and z ; rehash all items previously in j;

- Example 5: Suppose the hash function is $\boldsymbol{h}(\boldsymbol{x})=\boldsymbol{x}$ mod 8 and each bucket can hold at most two records. Show the extendable hash structure after inserting 1, 4, 5, 7, 8, 2, 20. $\begin{array}{llllllll}1 & 4 & 5 & 7 & 8 & 2 & 20 \\ 001 & 100 & 101 & 111 & 000 & 010 & 100\end{array}$




Suppose the hash function $h(x)=x \bmod 8$, each bucket can hold at most 2 records.

Show the structure after inserting " 20 "


